Lecture 13: Joins Part II

Today's Lecture

- 1. Sort-Merge Join (SMJ)
- 2. Hash Join (HJ)
- 3. The Cage Match: SMJ vs. HJ

Lecture 13 > Section 1

1. Sort-Merge Join (SMJ)



What you will learn about in this section

- 1. Sort-Merge Join
- 2. "Backup" & Total Cost
- 3. Optimizations
- 4. ACTIVITY: Sequential Flooding

Sort Merge Join (SMJ): Basic Procedure

To compute $R \bowtie S$ on A:

- 1. Sort R, S on A using *external merge sort*
- 2. Scan sorted files and "merge"
- 3. [May need to "backup"- see next subsection]

Note that if R, S are already sorted on A, SMJ will be awesome!

Note that we are only considering equality join conditions here

• For simplicity: Let each page be *one tuple*, and let the first value be A



1. Sort the relations R, S on the join key (first value)



2. Scan and "merge" on join key!



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2. Scan and "merge" on join key!



2. Done!



Lecture 13 > Section 1 > Backup

What happens with duplicate join keys?









Backup

- At best, no backup → scan takes P(R) + P(S) reads
 - For ex: if no duplicate values in join attribute
- At worst (e.g. full backup each time), scan could take P(R) * P(S) reads!
 - For ex: if *all* duplicate values in join attribute, i.e. all tuples in R and S have the same value for the join attribute
 - Roughly: For each page of R, we'll have to *back up* and read each page of S...
- Often not that bad however, plus we can:
 - Leave more data in buffer (for larger buffers)
 - Can "zig-zag" (see animation)

SMJ: Total cost

- Cost of SMJ is cost of sorting R and S...
- Plus the cost of scanning: ~P(R)+P(S)
 - Because of *backup*: in worst case P(R)*P(S); but this would be very unlikely
- Plus the **cost of writing out**: ~P(R)+P(S) but in worst case T(R)*T(S)

 \sim Sort(P(R)) + Sort(P(S)) + P(R) + P(S) + OUT Recall: Sort(N) $\approx 2N\left(\left[\log_{B} \frac{N}{2(B+1)}\right] + 1\right)$ Note: this is using repacking, where we estimate that we can create initial runs of length ~2(B+1)

SMJ vs. BNLJ: Steel Cage Match

- If we have 100 buffer pages, P(R) = 1000 pages and P(S) = 500 pages:
 - Sort both in two passes: 2 * 2 * 1000 + 2 * 2 * 500 = 6,000 IOs
 - Merge phase 1000 + 500 = 1,500 IOs
 - <u>= 7,500 IOs + OUT</u>

What is BNLJ?

- $500 + 1000*\left[\frac{500}{98}\right] = 6,500 \text{ IOs} + \text{OUT}$
- But, if we have 35 buffer pages?
 - Sort Merge has same behavior (still 2 passes)
 - BNLJ? <u>15,500 IOs + OUT!</u>

SMJ is ~ linear vs. BNLJ is quadratic... But it's all about the memory.



A Simple Optimization: Merges Merged!

Given **B+1** buffer pages

- SMJ is composed of a *sort phase* and a *merge phase*
- During the *sort phase*, run passes of external merge sort on R and S
 - Suppose at some point, R and S have <= **B** (sorted) runs in total
 - We could do two merges (for each of R & S) at this point, complete the sort phase, and start the merge phase...
 - OR, we could combine them: do **one** B-way merge and complete the join!





Simple SMJ Optimization

Given **B+1** buffer pages

- Now, on this last pass, we only do P(R) + P(S) IOs to complete the join!
- If we can initially split R and S into B total runs each of length approx. <= 2(B+1), assuming repacking lets us create initial runs of ~2(B+1)- then we only need 3(P(R) + P(S)) + OUT for SMJ!
 - 2 R/W per page to sort runs in memory, 1 R per page to B-way merge / join!
- How much memory for this to happen?
 - $\frac{P(R) + P(S)}{P} \le 2(B+1) \Rightarrow \sim P(R) + P(S) \le 2B^2$

See Lecture 13, Slide 13-14 – to clarify this slide.

• Thus, $max{P(R), P(S)} \le B^2$ is an approximate sufficient condition

If the larger of R,S has <= B² pages, then SMJ costs 3(P(R)+P(S)) + OUT!

Takeaway points from SMJ

If input already sorted on join key, skip the sorts.

- SMJ is basically linear.
- Nasty but unlikely case: Many duplicate join keys.

SMJ needs to sort **both** relations

• If max { P(R), P(S) } < B² then cost is 3(P(R)+P(S)) + OUT



Bonus questions.



- Q1: Fast dog.
 - If max $\{P(R), P(S)\} < B^2$ then SMJ takes 3(P(R) + P(S)) + OUT
 - What is the similar condition to obtain 5(P(R) + P(S)) + OUT?
 - What is the condition for (2k+1)(P(R) + P(S)) + OUT
- Q2: BNLJ V. SMJ
 - Under what conditions will BNLJ outperform SMJ?
 - Size of R, S and # of buffer pages
- Discuss! And We'll put up a google form.

Lecture 13 > Section 2

2. Hash Join (HJ)



What you will learn about in this section

- 1. Hash Join
- 2. Memory requirements

Recall: Hashing

• Magic of hashing:

- A hash function h_B maps into [0,B-1]
- And maps nearly uniformly
- A hash **collision** is when x = y but $h_B(x) = h_B(y)$
 - Note however that it will <u>**never**</u> occur that x = y but $h_B(x) != h_B(y)$
- We hash on an attribute A, so our has function is $h_B(t)$ has the form $h_B(t.A)$.
 - **Collisions** may be more frequent.

Recall: Mad Hash Collisions





Say something here to justify this slide's existence? [TODO]

To compute $R \bowtie S$ on A:

Note again that we are only considering equality constraints here

- Partition Phase: Using one (shared) hash function h_B, partition R and S into B buckets
- 2. Matching Phase: Take pairs of buckets whose tuples have the same values for *h*, and join these
 - Use BNLJ here; or hash again → either way, operating on small partitions so fast!

We *decompose* the problem using h_{B} , then complete the join

To compute $R \bowtie S$ on A:

- **1.** Partition Phase: Using one (shared) hash function h_B per pass partition R and S into **B** buckets.
 - Each phase creates B more buckets that are a factor of B smaller.
 - Repeatedly partition with a new hash function
 - Stop when all buckets for one relation are smaller than B-1 (Why?)

Each pass takes 2(P(R) + P(S))

- 2. Matching Phase: Take pairs of buckets whose tuples have the same values for *h*, and join these
 - Use BNLJ here for each matching pair.

P(R) + P(S) + OUT

We *decompose* the problem using h_B , then complete the join

1. Partition Phase: Using one (shared) hash function h_B , partition R and S into **B** buckets



2. Matching Phase: Take pairs of buckets whose tuples have the same values for h_B , and join these



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Goal: For each relation, partition relation into **buckets** such that if $h_B(t.A) = h_B(t'.A)$ they are in the same bucket

Given B+1 buffer pages, we partition into B buckets:

- We use B buffer pages for output (one for each bucket), and 1 for input
 - The "dual" of sorting.
 - For each tuple t in input, copy to buffer page for $h_B(t.A)$
 - When page fills up, flush to disk.

How big are the resulting buckets?

• Given N input pages, we partition into B buckets:

- → Ideally our buckets are each of size ~ N/B pages
- What happens if there are hash collisions?
 - Buckets could be > N/B
 - We'll do several passes...
- What happens if there are **duplicate join keys**?
 - Nothing we can do here... could have some **skew** in size of the buckets

Given *B***+1** buffer pages

How big *do we want* the resulting buckets?

- Ideally, our buckets would be of size $\leq B 1$ pages
 - 1 for input page, 1 for output page, **B-1** for each bucket
- Recall: If we want to join a bucket from R and one from S, we can do BNLJ in linear time if for one of them (wlog say R), $P(R) \leq B 1!$
 - And more generally, being able to fit bucket in memory is advantageous
- We can keep partitioning buckets that are > B-1 pages, until they are ≤ B − 1 pages
 - Using a new hash key which will split them...

We'll call each of these a "pass" again...



Given *B***+1** buffer pages

We partition into B = 2 buckets using hash function h_2 so that we can have one buffer page for each partition (and one for input)



For simplicity, we'll look at partitioning one of the two relations- we just do the same for the other relation!

Recall: our goal will be to get B = 2buckets of size $\leq B-1 \rightarrow 1$ page each

1. We read pages from R into the "input" page of the buffer...



2. Then we use **hash function** h_2 to sort into the buckets, which each have one page in the buffer



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Given *B***+1 = 3** buffer pages

3. We repeat until the buffer bucket pages are full...



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3. We repeat until the buffer bucket pages are full... then flush to disk



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Given *B***+1 = 3** buffer pages

Disk R BO B1

Note that collisions can occur!



Finish this pass...



Finish this pass...



Given *B***+1 = 3** buffer pages

Finish this pass...









Output (bucket) pages

Finish this pass...





We wanted buckets of size *B-1 = 1...* however we got larger ones due to:

(1) Duplicate join keys

(2) Hash collisions

Hash Join Phase 1: Partitioning Given B

Given *B***+1 = 3** buffer pages



To take care of larger buckets caused by (2) hash collisions, we can just do another pass!

What hash function should we use?

Do another pass with a different hash function, $h'_{2,}$ ideally such that:

 $h'_{2}(3) != h'_{2}(5)$

Hash Join Phase 1: Partitioning Given B

Given *B***+1 = 3** buffer pages



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What about duplicate join keys? Unfortunately this is a problem... but usually not a huge one.

We call this unevenness in the bucket size <u>skew</u>

Lecture 13 > Section 2 > HJ

Now that we have partitioned R and S...

• Now, we just join pairs of buckets from R and S that have the same hash value to complete the join!



- Note that since x = y → h(x) = h(y), we only need to consider pairs of buckets (one from R, one from S) that have the same hash function value
- If our buckets are ~B 1 pages, can join each such pair using BNLJ in linear time; recall (with P(R) = B-1):

BNLJ Cost:
$$P(R) + \frac{P(R)P(S)}{B-1} = P(R) + \frac{(B-1)P(S)}{B-1} = P(R) + P(S)$$

Joining the pairs of buckets is linear! (As long as smaller bucket <= B-1 pages)





$R \bowtie S \text{ on } A$

To perform the join, we ideally just need to explore the dark blue regions

= the tuples with same values of the join key A



$R \bowtie S \text{ on } A$

With a join algorithm like BNLJ that doesn't take advantage of equijoin structure, we'd have to explore this *whole grid!*

S.A hashed values

 $R \bowtie S \text{ on } A$

An alternative to applying BNLJ:

We could also hash again, and keep doing passes in memory to reduce further!

R.A hashed values

How much memory do we need for HJ?

- Given B+1 buffer pages + WLOG: Assume P(R) <= P(S)
- Suppose (reasonably) that we can partition into B buckets in 2 passes:
 - For R, we get B buckets of size ~P(R)/B
 - To join these buckets in linear time, we need these buckets to fit in B-1 pages, so we have:

$$B - 1 \ge \frac{P(R)}{B} \Rightarrow \sim B^2 \ge P(R)$$

Quadratic relationship between *smaller relation's* size & memory!

Hash Join Summary

- Given enough buffer pages as on previous slide...
 - **Partitioning** requires reading + writing each page of R,S
 - \rightarrow 2(P(R)+P(S)) IOs
 - Matching (with BNLJ) requires reading each page of R,S
 - \rightarrow P(R) + P(S) IOs
 - Writing out results could be as bad as P(R)*P(S)... but probably closer to P(R)+P(S)

HJ takes ~3(P(R)+P(S)) + OUT IOs!

Bonus questions #2

- Q1: Fast little dog.
 - If min $\{P(R), P(S)\} < B^2$ then HJ takes 3(P(R) + P(S)) + OUT
 - What is the similar condition to obtain 5(P(R) + P(S)) + OUT?
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- Q2: SMJ V. HJ
 - Under what conditions will HJ outperform SMJ?
 - Under what conditions will SMJ outperform SMJ?
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- Discuss! And We'll put up a google form.

Lecture 13 > Section 3 > The Cage Match

3. The Cage Match

Sort-Merge v. Hash Join

• *Given enough memory*, both SMJ and HJ have performance:

~3(P(R)+P(S)) + *OUT*

- "Enough" memory =
 - SMJ: B² > max{P(R), P(S)}
 - HJ: B² > min{P(R), P(S)}

Hash Join superior if relation sizes *differ greatly*. Why?

Further Comparisons of Hash and Sort Joins

• Hash Joins are highly parallelizable.

 Sort-Merge less sensitive to data skew and result is sorted

Summary

- Saw IO-aware join algorithms
 - Massive difference
- Memory sizes key in hash versus sort join
 - Hash Join = Little dog (depends on smaller relation)
- Skew is also a major factor
- Message: The database can compute IO costs, and these are different than a traditional system